# **W5500 TCP Function**

By setting some register and memory operation, W5500 provides internet connectivity. This chapter describes how it can be operated.

## Initialization

## **Basic Setting**

For the W5500 operation, select and utilize appropriate registers shown below.

- 1. Mode Register (MR)
- 2. Interrupt Mask Register (IMR)
- 3. Retry Time-value Register (RTR)
- 4. Retry Count Register (RCR)

For more information of above registers, refer to the "Register Descriptions."

## Setting network information

Basic network information setting for communication: It must be set the basic network information.

- 1. SHAR(Source Hardware Address Register)
  - It is prescribed that the source hardware addresses, which is set by SHAR, use unique hardware addresses (Ethernet MAC address) in the Ethernet MAC layer. The IEEE manages the MAC address allocation. The manufacturer which produces the network device allocates the MAC address to product.
  - Details on MAC address allocation refer to the website as below.
  - o http://www.ieee.org/
  - http://standards.ieee.org/regauth/oui/index.shtml
- 2. GAR(Gateway Address Register)
- 3. SUBR(Subnet Mask Register)
- 4. SIPR(Source IP Address Register)

## Set socket memory information

This stage sets the socket tx/rx memory information. The base address and mask address of each socket are fixed and saved in this stage.

#### In case of, assign 2KB rx, tx memroy per SOCKET

```
In case of, assign 2KB rx, tx memory per SOCKET
{
Sn_RXMEM_SIZE(ch) = (uint8 *) 2; // Assign 2K rx memory per SOCKET
Sn_TXMEM_SIZE(ch) = (uint8 *) 2; // Assign 2K rx memory per SOCKET
```

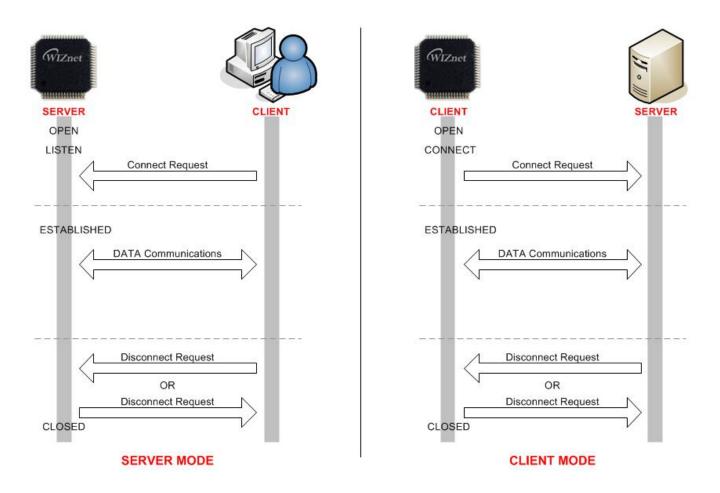
/\* Same method, set gS1\_TX\_BASE, gS1\_TX\_MASK, gS2\_TX\_BASE, gS2\_TX\_MASK, gS3\_TX\_BASE, gS3\_TX\_MASK, gS4\_TX\_BASE, gS4\_TX\_MASK, gS5\_TX\_BASE, gS5\_TX\_MASK, gS6\_TX\_BASE, gS6\_tx\_MASK, gS7\_TX\_BASE, gS7\_TX\_MASK \*/ }

## **Data Communications**

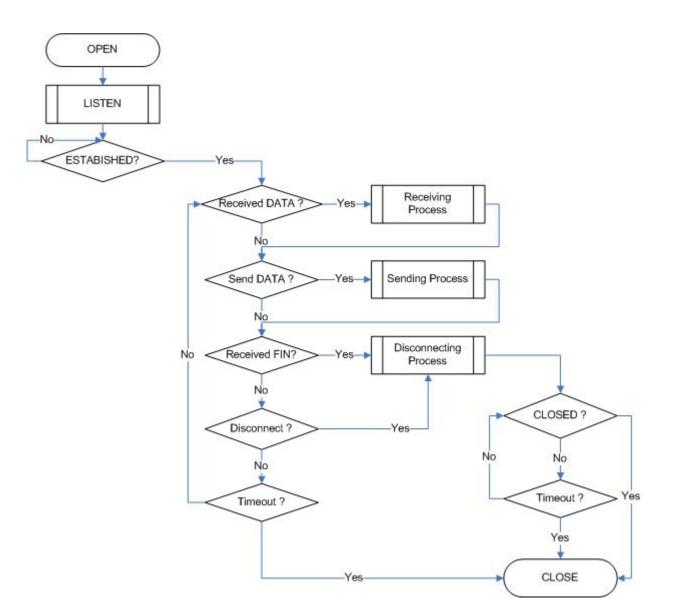
After the initialization process, W5500 can transmit and receive the data with others by 'open' the SOCKET of TCP, UDP, IPRAW, and MACRAW mode. The W5500 supports the independently and simultaneously usable 8 SOCKETS. In this section, the communication method for each mode will be introduced.

## ТСР

The TCP is a connection-oriented protocol. The TCP make the connection SOCKET by using its own IP address, port number and destination IP address, port number. Then transmits and receives the data by using this SOCKET. Methods of making the connection to SOCKET are "TCP SERVER" and "TCP CLIENT". It is divided by transmitting the connect-request (SYN packet). The "TCP SERVER" listens to the connect-request from the "TCP CLIENT", and makes connection SOCKET by accepting the transmitted connect-request (Passive-open). The "TCP CLIENT" transmits the connect-request first to "TCP SERVER" to make the connection (Active-open).



## **TCP SERVER**



#### **SOCKET** Initialization

SOCKET initialization is required for TCP data communication. The initialization is opening the SOCKET. The SOCKET opening process selects one SOCKET from 8 SOCKETS of the W5500, and sets the protocol mode (Sn\_MR) and Sn\_PORT0 which is source port number (Listen port number in "TCP SERVER") in the selected SOCKET, and then executes OPEN command. After the OPEN command, if the status of Sn\_SR is changed to SOCK\_INIT, the SOCKET initialization process is completed. The SOCKET initialization process is identically applied in "TCP SERVER" and "TCP CLIENT."The Initialization process of Socket n in TCP mode is shown below.

```
{
START:
Sn_MR = 0x01; // sets TCP mode
Sn_PORT0 = source_port; // sets source port number
Sn_CR = 0PEN; // sets OPEN command
/* wait until Sn_SR is changed to SOCK_INIT */
if (Sn_SR != SOCK_INIT) Sn_CR = CLOSE; goto START;
```

#### }

#### LISTEN

Run as "TCP SERVER" by LISTEN command.

{
 /\* listen SOCKET \*/
Sn\_CR = LISTEN;
 /\* wait until Sn\_SR is changed to SOCK\_LISTEN \*/
if (Sn\_SR != SOCK\_LISTEN) Sn\_CR = CLOSE; goto START;
}

#### ESTABLISHMENT

When the status of Sn\_SR is SOCK\_LISTEN, if it receives a SYN packet, the status of Sn\_SR is changed to SOCK\_SYNRECV and transmits the SYN/ACK packet. After that, the Socket n makes a connection. After it makes the connection of Socket n , it enables the data communication. There are two methods to confirm the connection of Socket n .

```
First method :
{
    if (Sn_IR(CON) == '1')
    /* When an interrupt occurs and the mask bit of Sn_IMR is '1', the interrupt
    bit of Sn_IR
    becomes '1' */
    Sn_IR(CON) = '1';
    /*In order to clear the Sn_IR bit, the host should write the bit as '1'.
    When all the bits of
    Sn_IR is cleared ('0'), IR(n) is automatically cleared.*/
    goto ESTABLISHED stage;
    /* In this case, if the interrupt of Socket n is activated, interrupt occurs.
    Refer to IR, IMR
    Sn_IMR and Sn_IR. */
    Second method :
    {
        if (Sn_SR == SOCK_ESTABLISHED) goto ESTABLISHED stage;
    }
}
```

#### ESTABLISHMENT : Check received data

Confirm the reception of the TCP data.

```
First method :
{
```

```
if (Sn_IR(RECV) == '1') Sn_IR(RECV) = '1'; goto Receiving Process stage;
/* In this case, if the interrupt of Socket n is activated, interrupt occurs.
Refer to IR, IMR
Sn_IMR and Sn_IR. */
}
Second Method :
{
if (Sn_RX_RSR0 != 0x0000) goto Receiving Process stage;
}
```

The First method: set the Sn\_IR(RECV) to '1' whenever you receive a DATA packet. If the host receives the next DATA packet without setting the Sn\_IR(RECV) as '1' in the prior DATA packet, it cannot recognize the Sn\_IR(RECV) of the next DATA packet. This is due to the prior Sn\_IR(RECV) and next Sn\_IR(RECV) being overlapped. So this method is not recommended if the host cannot perfectly process the DATA packets of each Sn\_IR(RECV).

#### **ESTABLISHMENT : Receiving process**

In this process, it processes the TCP data which was received in the Internal RX memory. At the TCP mode, the W5500 cannot receive the data if the size of received data is larger than the RX memory free size of Socket n . If the prior stated condition is happened, the W5500 holds on to the connection (pauses), and waits until the RX memory's free size is larger than the size of the received data.

```
{
    /* first, get the received size */
len = Sn_RX_RSR; // len is received size
    /* select RX memory, refer to Datasheet 14 page */
cntl_byte = Socket_n_RX_Buffer
    /* Get offset address */
src_ptr = Sn_RX_RD;
    /* set memory copy len bytes of source_ptr to destination_address */
for (i=0; i<len; i++)
{
    *(dst_ptr+i) = W5500_READ(addr, cntl_byte, src_ptr+i);
}
    /* increase Sn_RX_RD as length of len */
Sn_RX_RD += len;
    /* set RECV command */
Sn_CR = RECV;
}
</pre>
```

#### ESTABLISHMENT: Check send data / Send process

The size of the transmit data cannot be larger than assigned internal TX memory of Socket n. If the size of transmit data is larger than configured MSS, it is divided by size of MSS and transmits. To transmit the next data, user must check the completion of prior SEND command. An error may occur if the SEND command executes before completion of prior SEND command. The larger the data size, the more time to complete the SEND command. So the user should properly divide the data to

transmit.

To check the completion of the SEND command, it should be check that the send data length is equal with the actual sent data length. The actual sent data length is calculated by the difference of the Sn\_TX\_RD before and after performing the SEND command. If the actual sent data is less than the send data length, the SEND command is retried for sending the left data. The send process is therefore completed the SENDwhen the sum of the actual sent data is equal the send data length. A simple example of the send process is as below Ex) Send Data Length Size= 10,

1. Execute SEND Command with send data length

### 2. Calculate the actual sent data length

If the actual sent data length is 7 (= Sn\_TX\_RD\_after\_SEND-Sn\_TX\_RD\_befor\_SEND),

```
• the left Data length= 3
```

3. Retry SEND Command until the sum of the actual sent data length is same the send data length.

Note: Don't copy data until the sum of the actual sent data length is the send data length.

```
/* first, get the free TX memory size */
FREESIZE:
freesize = Sn TX FSR;
if (freesize<len) goto FREESIZE; // len is send size
/* select TX memory, refer to Datasheet 14 page */
cntl byte = Socket n TX Buffer
/* Get offset address */
dst ptr = Sn TX RD;
/* set memory copy len bytes of source ptr to destination address */
for (i=0; i<len; i++)</pre>
{
   W5500 WRITE(addr, cntl byte, dst ptr+i);
}
/* increase Sn TX WR as length of len */
Sn TX WR += send size;
/* set SEND command */
Sn CR = SEND;
/* return real packet size */
return len;
```

#### ESTABLISHMENT : Check disconnect-request(FIN packet)

Check if the Disconnect-request(FIN packet) has been received. User can confirm the reception of FIN packet as below.

```
First method :
{
```

```
if (Sn_IR(DISCON) == '1') Sn_IR(DISCON)='1'; goto CLOSED stage;
/* In this case, if the interrupt of Socket n is activated, interrupt occurs.
Refer to IR, IMR
Sn_IMR and Sn_IR. */
}
Second method :
{
if (Sn_SR == SOCK_CLOSE_WAIT) goto CLOSED stage;
}
```

#### ESTABLISHMENT : Check disconnect / disconnecting process

When the user does not need data communication with others, or receives a FIN packet, disconnect the connection SOCKET.

```
{
/* set DISCON command */
Sn_CR = DISCON;
}
```

#### ESTABLISHMENT : Check closed

Confirm that the Socket n is disconnected or closed by DISCON or close command.

```
First method :
{
    if (Sn_IR(DISCON) == '1') goto CLOSED stage;
/* In this case, if the interrupt of Socket n is activated, interrupt occurs.
Refer to IR, IMR
Sn_IMR and Sn_IR. */
}
Second method :
{
    if (Sn_SR == SOCK_CLOSED) goto CLOSED stage;
}
```

#### **ESTABLISHMENT:** Timeout

The timeout can occur by Connect-request(SYN packet) or its response(SYN/ACK packet), the DATA packet or its response(DATA/ACK packet), the Disconnectrequest FIN packet) or its response(FIN/ACK packet) and transmission all TCP packet. If it cannot transmit the above packets within 'timeout' which is configured at RTR and RCR, the TCP final timeout(TCP<sub>TO</sub>) occurs and the state of Sn\_SR is set to SOCK\_CLOSED. Confirming method of the TCP<sub>TO</sub> is as below:

```
First method :
{
```

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```
if (Sn_IR(TIMEOUT bit) == '1') Sn_IR(TIMEOUT)='1'; goto CLOSED stage;
/* In this case, if the interrupt of Socket n is activated, interrupt occurs.
Refer to IR, IMR
Sn_IMR and Sn_IR. */
}
Second method :
{
if (Sn_SR == SOCK_CLOSED) goto CLOSED stage;
}
```

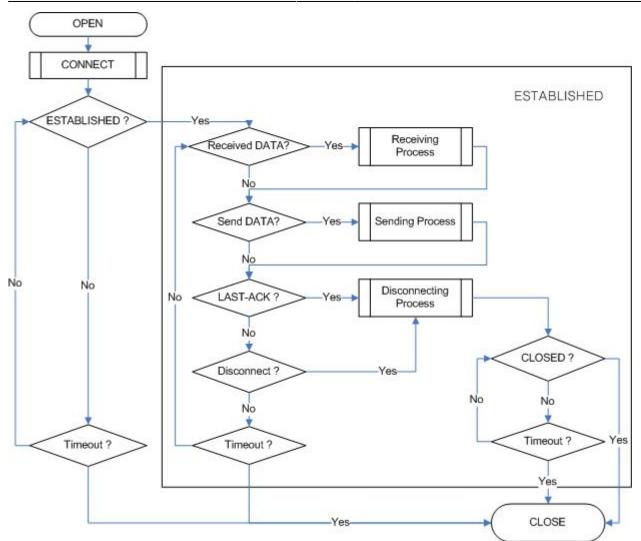
#### SOCKET Close

It can be used to close the Socket n , which disconnected by disconnect-process, or closed by  $TCP_{\tau_0}$  or closed by host's need without disconnect-process.

```
{
  /* clear the remained interrupts of Socket n */
Sn_IR = 0xFF;
IR(n) = '1';
/* set CLOSE command */
Sn_CR = CLOSE;
}
```

## **TCP CLIENT**

It is same as TCP server except 'CONNECT' state. User can refer to the above "TCP SERVER" section. TCP SERVER



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#### CONNECT

Transmit the connect-request (SYN packet) to "TCP SERVER". It may occurs the timeout such as  $ARP_{TO}$ , TCP<sub>TO</sub> when make the "connection SOCKET" with "TCP SERVER"

```
{
Sn_DIPR0 = server_ip; /* set TCP SERVER IP address*/
Sn_DPORT0 = server_port; /* set TCP SERVER listen port number*/
Sn_CR = CONNECT; /* set CONNECT command */
}
```

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